# Porting Mathlib

#### Mario Carneiro

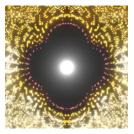
Carnegie Mellon University

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# Acknowledgements

- This is reporting on an unfinished project
- Joint work with Daniel Selsam, Aurélien Saue, Gabriel Ebner, Wojciech Nawrocki, Kevin Buzzard, David Renshaw, Jeremy Avigad, Deniz Aydin, Shing Tak Lam
- and many more are likely to enter the project later
- Funded by Microsoft Research

# Who am I?

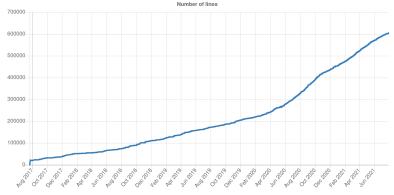


Github: digama0 Zulip: Mario Carneiro

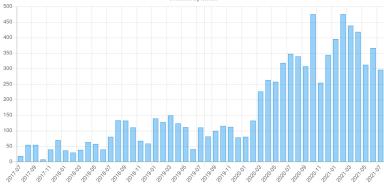
- PhD student in Logic at CMU
- Proof engineering since 2013
  - Metamath (maintainer)
  - Lean 3 mathlib (founder, maintainer)
  - Dabbled in Isabelle, HOL Light, Coq, Mizar
  - Metamath Zero (author)
- Proved 37 of Freek's 100 theorems list in Metamath
- Lots of library code in mathlib
- Say hi at https://leanprover.zulipchat.com

# Mathlib

- Library of formalized mathematics and computer science
- Lean 3 proof assistant
- de-facto standard library
- Based on Dependent type theory (CIC)
- Uses classical logic (and choice)
- Active community
  - github.com/leanprover-community/mathlib
  - leanprover.zulipchat.com



https://leanprover-community.github.io/mathlib\_stats.html



Commits by month

https://leanprover-community.github.io/mathlib\_stats.html

# Mathlib goals

Two main goals:

- (CS) To build a standard library for lean as a programming language
  - To support verified programming and proven-correct algorithms
  - To support and provide tactics and decision procedures for proof automation
- (Math) To build a library of formalized mathematics, and support users doing the same

These goals complement each other, it is not just two libraries in one

# Mathlib goals: 3 years later

I wrote those goals in a presentation three years ago, and the Math goal has seen considerably more attention than the CS goal, for several reasons:

- The name
- Effective marketing to mathematicians by Kevin Buzzard et al. have skewed the composition of mathlib contributors much farther towards pure mathematicians than comparable formal libraries in other communities
- Poor performance of the lean 3 interpreter means that optimized and verified data structures aren't really worth it

I expect that Lean 4 will push the balance towards more CS applications.

# More Mathlib projects

A number of notable projects have been done within or using mathlib:

- Schemes in Lean (v1: Kevin Buzzard, Chris Hughes, Kenny Lau; v2: Amelia Livingston, Ramon Fernández Mir; v3: Scott Morrison)
- Formalising perfectoid spaces (Kevin Buzzard, Johan Commelin, Patrick Massot)
- A formal proof of the independence of the continuum hypothesis (Jesse Michael Han, Floris van Doorn)
- Liquid Tensor Experiment (Johan Commelin, Peter Scholze, Patrick Massot, Adam Topaz, Riccardo Brasca, Kevin Buzzard, Bhavik Mehta, Scott Morrison, Damiano Testa, Heather Macbeth, Filippo A.E. Nuccio, et al)
  - This one has even been the subject of several news articles

# A Short History of Lean and mathlib

Several major versions:

- Lean 1 (2013 no public release)
- Lean 2 (2015) includes HoTT mode
- Lean 3 (2017)
- Lean 4 (2021, alpha)
- The Lean 2 math library was developed by Jeremy Avigad, Floris van Doorn, Rob Lewis et al.
- Lean 3 is not backwards compatible with Lean 2, and the decision was made to start again taking advantage of significant new features
- mathlib is the latest version of the Lean 3 math library, developed by hundreds of contributors
- Lean 4 is not backwards compatible with Lean 3, and the decision was made to port the library

# The Lean $2 \rightarrow$ Lean 3 transition

- Lean 3 added a number of features around the metaprogramming framework
- But the elaborator was scaled back significantly to avoid excessive backtracking that caused bad error messages and flaky scripts
- Reinterpreted Lean 2 files would generally have an error on every other lemma, and there were some small syntax differences as well, so manual porting required heavy touch-ups
- Mathlib was loosely based on the lean 2 library, but was written by hand from scratch
- Lean 2 library is about 40K lines; this was all eventually ported to mathlib within the first year (important stuff right away, other stuff later for completeness)

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- Lean 2 library is about 40K lines; this was all eventually ported to mathlib within the first year (important stuff right away, other stuff later for completeness)
- Mathlib is now 600K lines, up from 450K at Jan 2021

# Lean 4

- A complete reimplementation of Lean in Lean by Leonardo de Moura and Sebastian Ullrich
- Implementation started in 2018, first stable version released Jan 2021
- Endlessly extensible third party libraries like mathlib can override or extend almost any part of the system
- Compiles to C, so no more slow interpreted tactics
- A much more powerful macro / syntax engine, for first class DSL support
- do notation is significantly more powerful

#### Lean $3 \rightarrow$ Lean 4 differences

- Lean 4 is "inspired" by lean 3, it is not a direct upgrade and there is no backward compatibility
  - The basic concepts of theorems, definitions, expressions, tactics, attributes all have equivalents, but many things are moved around
- The lean 4 kernel is (mostly) an extension of the lean 3 kernel
  - Nested and mutual inductives
  - Natural number and string literals (with builtin bignum arithmetic)
  - Lean 3 "macros" are handled differently
  - Opaque definitions (constant)
  - A kernel primitive for trusting the evaluation of a compiled lean expression

# Lean $3 \rightarrow$ Lean 4 differences

- Lots of minor syntax changes
  - by tacs instead of begin tacs end
  - match doesn't have an end
  - fun  $x \Rightarrow e$  instead of  $\lambda x$ , e
  - Much more reliance on whitespace sensitivity over punctuation delimiters
- Tactics are now integrated with macros
- Elaboration is sometimes stronger, sometimes weaker
- Typeclass inference is different
- Many lean 3 tactics don't exist yet in lean 4
  - Some are omitted on purpose, either because they can be implemented by users (aka mathlib) or we have a better but incompatible design now

Porting strategies

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- The result is a set of compiled .olean files that can be imported into lean 4 files

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  - Some alignments are completely different, e.g. + is heterogeneous in lean 4

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  - And if they don't, we can make them leave more explicit annotations

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Definitions by pattern matching are already compiled

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- This is a very flexible approach, since it means we can just have #lang lean3 sections in a lean 4 file
- Or we can target it on full files, and either translate them to lean 4 syntax or just run and import them
- Lean 4 has a focus on versatile syntax parsing, and it is already being used to implement a parser very similar to lean 3 (namely lean 4)

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In short, to parse lean 3 you have to be lean 3

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  - parsers can't change the environment (they are non-monadic)

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- This ensures that we perfectly mimic any lean 3 parser oddities, since lean 3 is doing the parsing
- We can get access to all sorts of syntax not available with previous approaches:
  - Tactic block structure
  - Pattern matching definitions
  - Variables, sections, local notations

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- Some commands manipulate lean 3 state that is expressed differently in lean 4, like precedence
  - Should we just delete these?

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- ▶ No startup cost besides training people to write lean 4 code

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- lean3-port: Lean 3 re-parsing
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- synport: Translating lean 3 AST data into lean 4 source files
  - Uses lean --ast, implemented in a fork of lean 3
  - Provides a starting point for manual editing

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- Manage alignments through #align annotations in ported files
  - Useful for binport to be able to stay in sync
  - Still usable even if the alignments are not defeq as long as downstream uses are also realigned

# Translation examples: lt\_or\_ge

```
-- Lean 3
protected lemma lt_or_ge : \forall (a b : \mathbb{N}), a < b \vee b \leq a
| a 0 := or.inr (zero_le a)
| a (b+1) :=
  match lt_or_ge a b with
  | or.inl h := or.inl (le_succ_of_le h)
  | or.inr h :=
    match nat.eq_or_lt_of_le h with
    | or.inl h1 := or.inl (h1 ▷ lt_succ_self b)
    | or.inr h1 := or.inr h1
    end
  end
-- | ean 4
protected theorem lt_or_ge : (a b : \mathbb{N}) \rightarrow a < b \vee b \leq a
| a, 0 => Or.inr (zero_le a)
| a, b + 1 =>
  match lt_or_ge a b with
  | Or.inl h => Or.inl (le_succ_of_le h)
  | Or.inr h \Rightarrow
    match nat.eq_or_lt_of_le h with
    | Or.inl h1 => Or.inl (h1 ▷ lt_succ_self b)
    | Or.inr h1 => Or.inr h1
```

### Translation examples: div\_inv\_monoid

-- Lean 3 /-- A div inv monoid is a monoid with operations  $^{-1}$  and  $^{-1}$ @[protect proi, ancestor monoid has inv has div] class div\_inv\_monoid (G : Type u) extends monoid G, has\_inv G, has\_div G :=  $(div := \lambda a b, a * b^{-1})$  $(div_eq_mul_inv : \forall a b : G, a / b = a * b^{-1} . try_refl_tac)$ (gpow :  $\mathbb{Z} \to G \to G :=$  gpow rec) (gpow\_zero' : ∀ (a : G), gpow 0 a = 1 . try\_refl\_tac) (gpow\_succ' :  $\forall$  (n :  $\mathbb{N}$ ) (a : G), gpow (int.of nat n.succ) a = a \* gpow (int.of nat n) a . try refl tac) (gpow\_neg' :  $\forall$  (n :  $\mathbb{N}$ ) (a : G), gpow (-[1+ n]) a = (gpow n.succ a)  $^{-1}$  . try\_refl\_tac) -- Lean 4 /-- A `DivInvMonoid` is a `Monoid` with operations `/` and `-1`... -/ @[protectProil] class DivInvMonoid (G : Type u) extends Monoid G, Inv G, Div G where div := fun a b  $\Rightarrow$  a \* b<sup>-1</sup> div\_eq\_mul\_inv : (a b : G)  $\rightarrow$  a / b = a \* b<sup>-1</sup> := by try\_refl tac gpow :  $\mathbb{Z} \to G \to G := \text{gpow}_{rec}$ gpow zero' : (a : G)  $\rightarrow$  gpow 0 a = 1 := by try refl tac gpow\_succ' : (n :  $\mathbb{N}$ )  $\rightarrow$  (a : G)  $\rightarrow$  gpow (int.of\_nat n.succ) a = a \* gpow (int.of\_nat n) a := by try refl tac gpow neg': (n :  $\mathbb{N}$ )  $\rightarrow$  (a : G)  $\rightarrow$  gpow -[1+ n] a = (gpow n.succ a)<sup>-1</sup> := by try refl tac

### Translation examples: nat.mod\_lt

```
-- Lean 3
lemma mod lt (x : nat) {v : nat} (h : 0 < v) : x % v < v :=
begin
  induction x using nat.case strong induction on with x ih.
  { rw zero mod, assumption }.
  { by_cases h_1 : succ x < y,
    { rwa [mod_eq_of_lt h1] },
    { have h_1 : succ x % y = (succ x - y) % y := mod_eq_sub_mod (not_lt.1 h_1),
      have : succ x - y \le x := le_of_lt_succ (sub_lt (succ_pos x) h),
      have h_2: (succ x - y) % y < y := ih _ this,
      rwa [\leftarrow h<sub>1</sub>] at h<sub>2</sub> } }
end
-- Lean 4
theorem mod_lt (x : Nat) {y : Nat} (h : 0 < y) : x % y < y := by
  induction' x using Nat.case_strong_induction_on with x ih

    rw [zero_mod]; assumption

  · byCases h_1 : succ x < y

    rwa [mod eq of lt h₁]

    • have h_1 : succ x % y = (succ x - y) % y := mod_eq_sub_mod (not_lt.1 h_1)
      have : succ x - y \le x := le_of_lt_succ (sub_lt (succ_pos x) h)
      have h_2: (succ x - y) % y < y := ih this
      rwa [\leftarrow h_1] at h_2
```

### Conclusion

- This is quite possibly the largest source-level proof porting project ever
- Mathlib's high (and growing) activity rate and many contributors lead to some logistical challenges
- The techniques discussed here apply generally to any source-level translations
  - Lean 3 is in many ways a worst case for this kind of job
  - even translating Coq or Isabelle to Lean would follow a similar path

### Conclusion

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- The techniques discussed here apply generally to any source-level translations
  - Lean 3 is in many ways a worst case for this kind of job
  - even translating Coq or Isabelle to Lean would follow a similar path
- We really hope we don't have to do this again in lean 5

#### Resources

- Lean/mathlib: http://leanprover-community.github.io/
- Lean 4: https://github.com/leanprover/lean4/
- Mathport: https://github.com/dselsam/mathport
- Zulip: https://leanprover.zulipchat.com/
  - Porting discussions are on #lean4 and #mathlib4 streams

# Thanks!